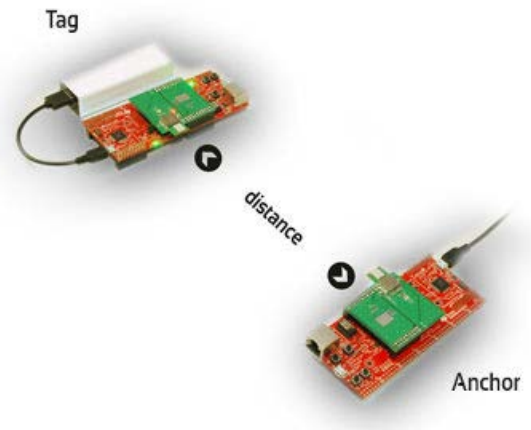


Evaluation and Development Platform

- Precise wireless distance measurement
- Unaffected by light conditions, weather or vibration
- COM (USB) for measurement and configuration compliant with IEEE 802.15.4a UWB PHY
- UWB PHY 110/850/6800 kbps
- Wide ecosystem of extension modules such as Wi-Fi, sensors, LCD
- JTAG programmer/debugger included
- **Source code in C includes Two Way Ranging project for Code Composer Studio**

Plug and play solution

Easy start with UWB technology



UWB Two Way Ranging (TWR) kit is the first full-featured platform for Ultra Wide Band distance measurement evaluation and its further development. Knowledge of precise distance might bring added value for many applications such as protection system, real-time localization and tracking system, robots navigation, etc.

Kit is built on the top of Tiva C microcontroller ecosystem, which brings various [sensor, communication and actuator boards](#) together with extensive open-source C [library](#) supported directly from Texas Instruments. This platform includes all the required communication interfaces for backhaul system such as Ethernet, USB and socket for WiFi module. All source codes for those interfaces are available.

UWB radio is configurable from a terminal where user may set one of six channels, preamble length or device role. The device might act in mode Anchor or Tag. According to settings, the communication might be fully set u to comply with IEEE [802.15.4a standard](#)

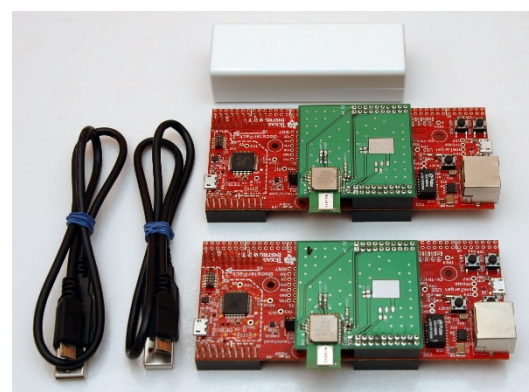
Platform Features

MCU platform	ARM-M4 Cortex TM4C1294
Radio	UWB 802.15.4a, DWM1000
Accuracy	+/- 15 cm *
Distance	Up to 50m (LOS)

*depends on radio configuration, calibration and environment

Package Content

1x	UWB Tag (preloaded firmware)
1x	UWB Anchor (preloaded firmware)
1x	Li-ion USB Battery 2200mAh
1x	Access to source code
2x	USB Micro cables

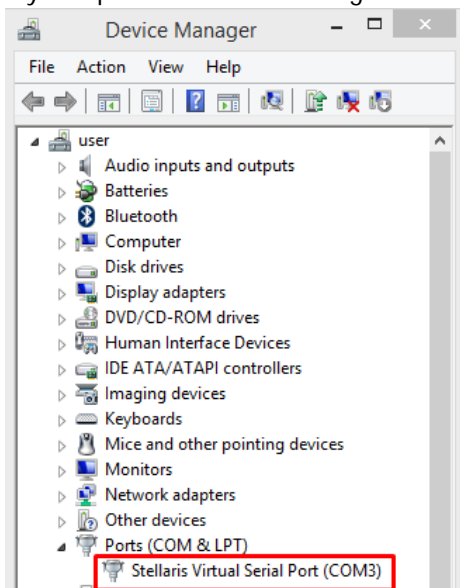


Requirements

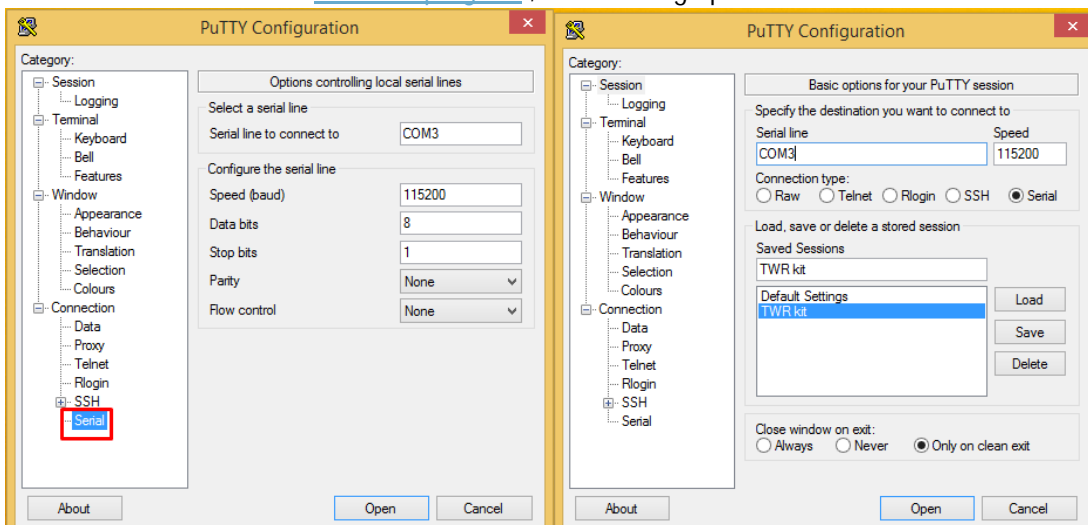
- Windows XP or higher
- USB port
- Terminal Program

Getting Started

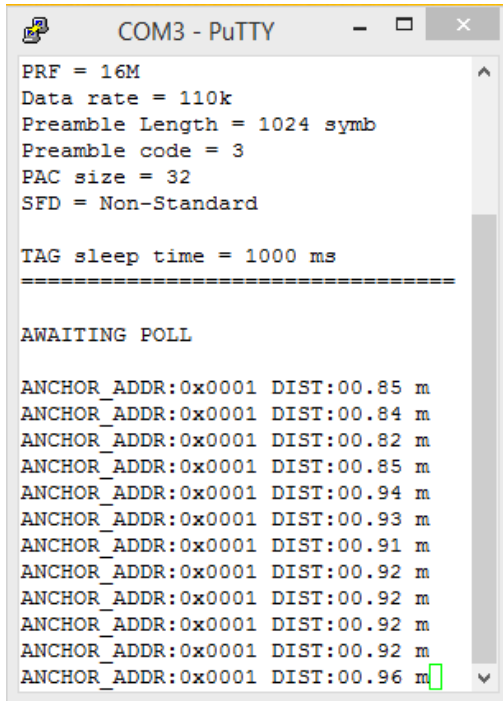
1. Connect UWB Anchor to micro USB port.
There are two ports available, the USB port farther from Ethernet connector must be used.
2. Install Virtual COM Port [drivers](#)
In case of problems please follow [this guide](#).
3. Identify COM port number
My computer -> Device Manager



4. Download and run PuTTY [Terminal program](#) , set following options:



5. Connect battery to UWB Tag
6. Address of Anchor and its distance from Tag should be immediately displayed in Terminal



The screenshot shows a PuTTY terminal window titled "COM3 - PuTTY". The terminal output displays the following configuration and data:

```
PRF = 16M
Data rate = 110k
Preamble Length = 1024 symb
Preamble code = 3
PAC size = 32
SFD = Non-Standard

TAG sleep time = 1000 ms
=====

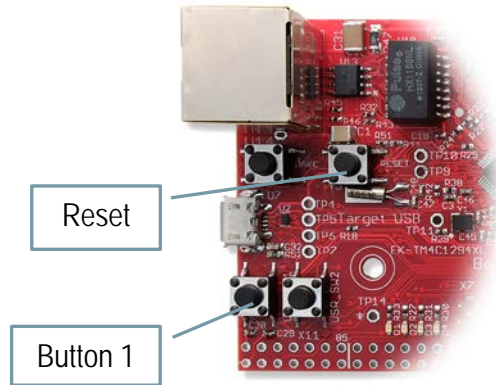
AWAITING POLL

ANCHOR_ADDR:0x0001 DIST:00.85 m
ANCHOR_ADDR:0x0001 DIST:00.84 m
ANCHOR_ADDR:0x0001 DIST:00.82 m
ANCHOR_ADDR:0x0001 DIST:00.85 m
ANCHOR_ADDR:0x0001 DIST:00.94 m
ANCHOR_ADDR:0x0001 DIST:00.93 m
ANCHOR_ADDR:0x0001 DIST:00.91 m
ANCHOR_ADDR:0x0001 DIST:00.92 m
ANCHOR_ADDR:0x0001 DIST:00.92 m
ANCHOR_ADDR:0x0001 DIST:00.92 m
ANCHOR_ADDR:0x0001 DIST:00.92 m
ANCHOR_ADDR:0x0001 DIST:00.92 m
ANCHOR_ADDR:0x0001 DIST:00.96 m
```

TAG / ANCHOR Communication Settings

To enter the Configuration mode, please follow these steps :

1. Connect Tag or Anchor to USB port of PC
2. Run terminal program, set appropriate COM port
3. Hold USER_BUTTON1 and press RESET for a short while



4. Current settings should be written in the terminal

```
COM3 - PuTTY
Sewio Ranging kit
Version 2.19 TIVA_C

===== Actual configure =====
Instance mode = ANCHOR
Channel = 2
PRF = 16M
Data rate = 110k
Preamble Length = 1024 symb
Preamble code = 3
PAC size = 32
SFD = Non-Standard

TAG sleep time = 1000 ms
=====
AWAITING POLL
█
```

5. Follow the instruction in order to change configuration.
Settings are automatically stored in MCU Flash memory

Default Settings

Channel = 1
Data rate = 110k
Preamble Length = 1024
Preamble code = 1
PAC size = 32
SFD = Non-Standard
TAG sleep time = 1 s

Configurable Options

- Channels

Channel	Center Frequency (MHz)	Band (MHz)	Bandwidth (MHz)
1	3494.4	3244.8 – 3744	499.2
2	3993.6	3774 – 4243.2	499.2
3	4492.8	4243.2 – 4742.4	499.2
4	3993.6	3328 – 4659.2	1331.2 (real approx. 900)
5	6489.6	6240 – 6739.2	499.2
7	6489.6	5980.3 – 6998.9	1081.6 (real approx. 900)

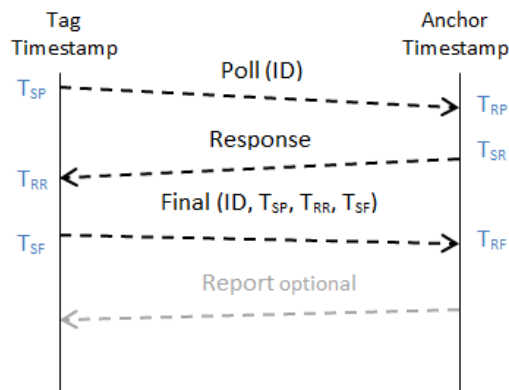
- Preamble length
2048, 1536, 1024, 512, 256, 128, 64
- Data Rate
110 / 850 / 6800 kbps
- TAG sleep time
0.1 – 30s (step of XXX ms)
- Device Role
TAG / ANCHOR

Brief Principle of Distance Measurement

Three messages Poll, Response, Final are exchanged between Tag and Anchor in order to get a precise distance. Distance is calculated based on Tag (T_{SP} , T_{RR} , T_{SF}) and Anchor (T_{RP} , T_{SR} , T_{RF}) timestamps. Calculation is done by Anchor therefore Report message might be employed in order to transmit distance measurement from Anchor back to Tag.

$$\text{Distance} = \text{ToF} * \text{speed of light}$$

$$\text{ToF} = ((T_{RR} - T_{SP}) - (T_{SR} - T_{RP}) + (T_{RF} - T_{SR}) - (T_{SF} - T_{RR})) / 4$$

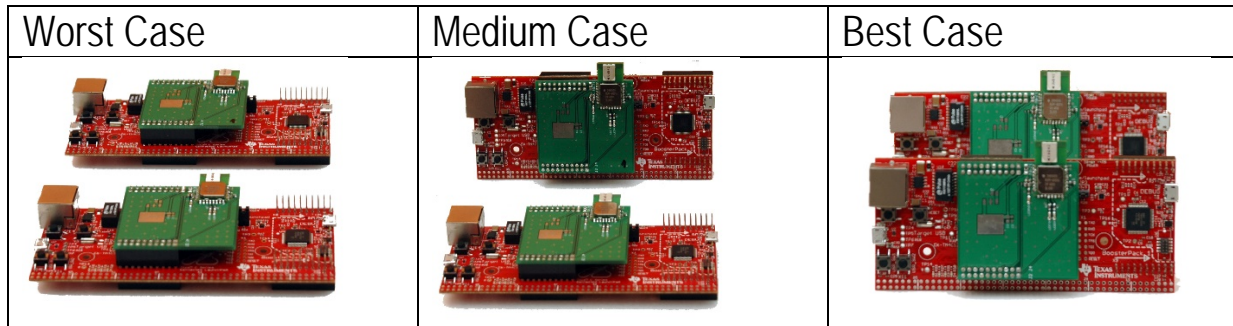


Ranging messages are encapsulated within 802.15.4 frame, see details in picture below:







IEEE 802.15.4 Frame	2 Bytes	1 Byte	2 Bytes	2/8 Bytes	2/8 Bytes	2 Bytes
	Frame Control	Sequence Number	PAN ID	Destination Address	Source Address	FCS
	Payload					
Poll Message	1 Byte	0-85 Bytes				
	Packet ID	User Payload				
	0x21	-	-	-	-	-
Response Message	1 Byte	1 Byte	2 Byte	0-85 Bytes		
	Packet ID	Activity	Activity Parameter	User Payload		
	0x10	0x02	0x0000	-		
Final Message	1 Byte	6 Bytes	6 Bytes	6 Bytes	0-85 Bytes	
	Packet ID	Poll Message Tx Timestamp	Response Message RX Timestamp	Predicted Final TX Timestamp	User Payload	
	0x29	-	-	-	-	-
Report Message	1 Byte	6 Bytes	0-85 Bytes			
	Packet ID	Calculated ToF	User Payload			
	0x2A	-	-	-	-	-

Practical Aspects for Consideration

Chip Antenna Orientation vs Distance Measurement Performance

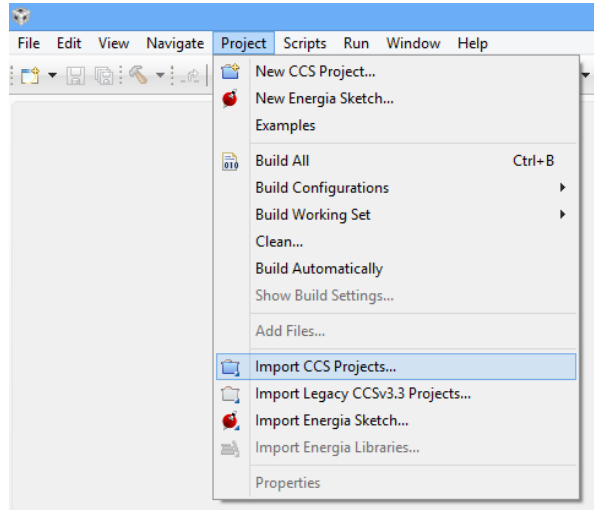


UWB Communication Parameters Tradeoff

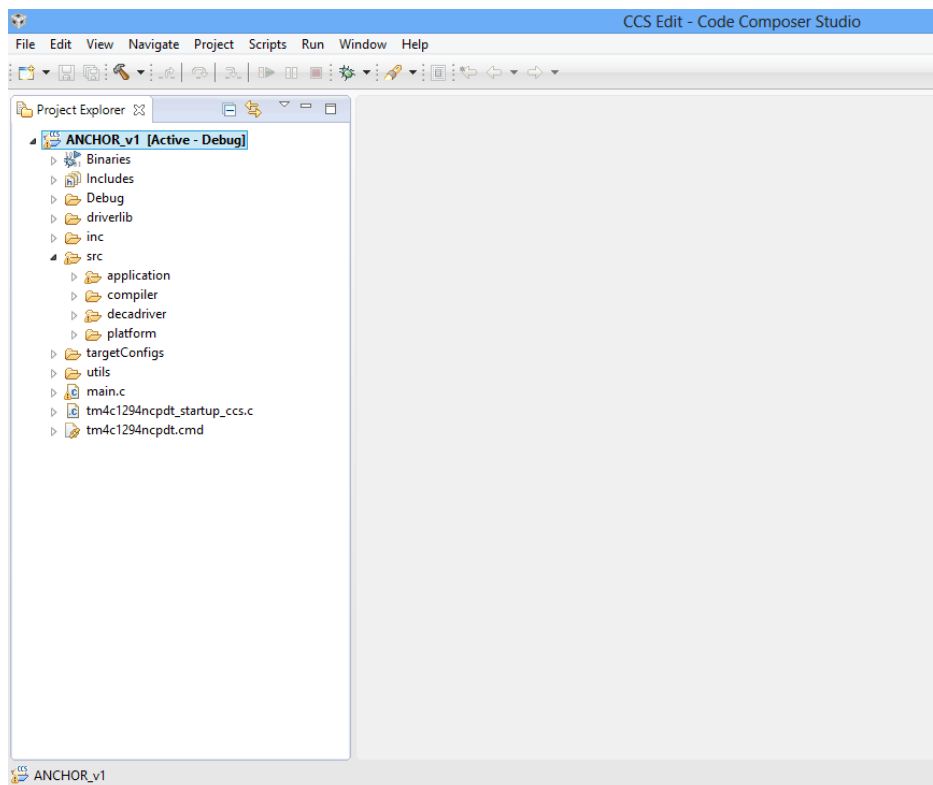
	High Data Rate & Low Preamble Size		Low Data Rate & Big Preamble Size
	Short Communication Range		Long Communication Range
	Low Power Consumption		High Power Consumption

Ranging Source Code

1. Download, install and run [Code Composer Studio](#) for Tiva platform.
2. Download and extract TWR source code, *link is provided within TWR kit*
3. Import TWR source code project named ANCHOR to Code Composer Studio



4. See project folder structure



Useful Documentation

UWB Two Way Ranging

Datasheet

<p><i>Creating IoT Solutions with the TM4C1294XL Connected LaunchPad Workshop</i></p> <p>Step by step video tutorial describing all MCU peripherals within 16 chapters</p> <ol style="list-style-type: none"> 1. Intro to TM4C Devices, LaunchPad and Cloud Services 2. Intro to Code Composer Studio 3. TivaWare, Initialization and GPIO 4. Ethernet Port 5. Interrupts and the Timers 6. ADC and the Educational Boosterpack 7. PWM and QEI 8. I2C, SensorLib and GUI Composer 9. SPI and the QSSI 10. UART 11. USB 12. Memory, Security and the MPU 13. Floating Point Unit 14. DMA 15. Low Power Modes 16. Graphics Library 	<p><u>link</u></p>
<p><i>TivaWare drivers for peripherals, USB (Host, Device and On-the-Go), Graphics Library and Examples</i></p>	<p><u>link</u></p>
<p><i>UWB Radio DWM1000 Datasheet</i></p>	<p><u>link</u></p>
<p><i>IEEE 802.15.4a (2011)</i></p>	<p><u>link</u></p>

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